Docket No.: 44084-468

**UTILITY PATENT APPLICATION
UNDER 37 CFR 1.53(b)**

Box PATENT APPLICATION
Assistant Commissioner for Patents
Washington, DC 20231
Sir:

Transmitted herewith for filing is the patent application of:

      INVENTOR: Hiroki YOSHIDA
      FOR: IMAGE PROCESSING APPARATUS AND METHOD

Enclosed are:

☒ 22 pages of specification, claims, abstract.
☒ Declaration and Power of Attorney.
☒ Priority Claimed.
☒ Certified copy of   Japanese Patent Application No. 11-229181
☒ 8 sheets of formal drawing.
☒ An assignment of the invention to   MINOLTA CO., LTD.
    and the assignment recordation fee.
☐ An associate power of attorney.
☐ A verified statement to establish small entity status under 37 CFR 1.9 and 37 CFR 1.27.
☒ Information Disclosure Statement, Form PTO-1449 and reference.
☒ Return Receipt Postcard
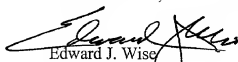☐

The filing fee has been calculated as shown below:

	NO. OF CLAIMS		EXTRA CLAIMS	RATE	AMOUNT
Total Claims	10	-20	0	$18.00	$0.00
Independent Claims	0	-3	1	$78.00	$78.00
			Multiple Dependent Claim(s)		$0.00
				Basic Fee	$690.00
			Total of Above Calculations		$768.00
			Less ½ for Small Entity		$0.00
			Assignment & Recording Fee		$40.00
			Total Fee		**$808.00**

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    ☒ Any filing fees under 37 CFR 1.16 for presentation of extra claims.

Respectfully submitted,

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IMAGE PROCESSING APPARATUS AND METHOD

The present application claims priority to
Japanese Patent Application No. 11-229181 filed August 13,
5   1999, the entire content of which is hereby incorporated
by reference.

BACKGROUND OF THE INVENTION

FIELD OF THE INVENTION

10 The present invention relates to a digital
image edge enhancement process.

DESCRIPTION OF THE RELATED ART

Digital images input from a digital camera and
15 the like are subjected to various types of image
correction.   Various methods are used in the edge
enhancement process, which is one of these image
correction processes.   For example, the edge is
determined to be between pixels in the image process
20 disclosed in Japanese Laid-Open Patent No. 5-108823.
Furthermore, a threshold value which determines the edge
is automatically calculated in the image process
disclosed in Japanese Laid-Open Patent 10-143673.

Generally, when enhancing the sharpness of a
25 digital image by an edge enhancement process, it is

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desirable to adjust the thickness of the edge, i.e., the range of edge enhancement, in accordance with the characteristics of the photographic object. For example, when photographing a building or man-made object, the image appears to have an added border when the line of the contour of the building is thickened, such that the image appears unnatural. Accordingly, it is desirable to enhance the line by narrowing the edge enhancement range so as to not thicken the line in the case of buildings and the like. Conversely, when enhancing an edge by thinning the edge in the case of a human image and the like, the enhancement often produces the opposite effect of making the eyes and the like appear unnatural. For this reason it is desirable to smoothly enhance the edge by broadening the width of the edge in the case of human images. That is, when photographing people, the enhancement range must be somewhat broadened with moderate edge enhancement. Numerous methods of automatic edge enhancement have been proposed heretofore, but the enhancement range must be input manually.

SUMMARY OF THE INVENTION

An object of the present invention is to provide an image processing apparatus capable of automatically accomplishing suitable edge enhancement.

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Another object of the present invention is to provide an image processing apparatus capable of excellent edge enhancement for human images as well as image of man-made objects.

5   These and other objects are attained by an image processing apparatus, comprising edge detecting means for determining the presence/absence of an edge at each pixel of input image data; selecting means for selecting a weighting matrix corresponding to the position of the edge of each target pixel determined to

10   have an edge by the edge detecting means; calculating means for calculating data of the target pixel and the pixels surrounding the target pixel using the weighting matrix selected by the selecting means; enhancement range

15   determining means for determining the range of edge enhancement of the target pixel by comparing the calculation result of the calculating means to a specific threshold value; and edge enhancing means for executing an edge enhancement process on data of object pixels

20   within the enhancement range determined by the enhancement range determining means.

The present invention is a medium readable by a computer storing computer-executable programs comprising the steps of determining the presence/absence of an edge

25   at each pixel of input image data; selecting a weighting

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matrix corresponding to the position of the edge for each target pixel determined to have an edge; calculating data of the target pixel and pixels surrounding the target pixel using selected weighting matrix; comparing the calculation result to a specific threshold value; determining the range of edge enhancement for the target pixel based on the comparison result; and executing an edge enhancement process for the object pixels within the determined enhancement range.

It is desirable that the enhancement range determining means increases the weighting of components corresponding to the interior side of the edge in the weighting matrix.

It is further desirable that the enhancement range determining means selects a weighting matrix based on the presence/absence of an edge in four directions surrounding the target pixel.

It is further desirable that the edge enhancing means executes processing based on the hue and chroma of the pixels surrounding the object pixel.

It is even further desirable that the edge enhancing means executes processing based on the distance of the object pixel to the target pixel.

The invention itself, together with further objects and attendant advantages, will be best understood

by reference to the following detailed description taken
in conjunction with the accompanying drawings.

BRIEF DESCRIPTION OF THE DRAWINGS

5   FIG. 1 shows the overall construction of an
image processing apparatus;

FIG. 2 is a block diagram of the image
processing apparatus;

FIG. 3 is a flow chart of edge enhancement;

10   FIG. 4 shows the coordinates within a block of
3×3 pixels;

FIGS. 5A through 5D show the edge detection
matrices;

FIG. 6 shows one example of an enhanced pixel;

15   FIG. 7 shows the target pixel and the edge
position;

FIG. 8 shows the target pixel and the edge
position;

FIG. 9 shows the target pixel and the edge
20   position;

FIG. 10 shows the target pixel and the edge
position;

FIG. 11 shows the coordinates within a block of
5×5 pixels;

FIGS. 12A through 12D show examples of weighting matrices; and

FIG. 13 shows an edge enhancement matrix.

In the following description, like parts are designated by like reference numbers throughout the several drawings.

DETAILED DESCRIPTRION OF THE PREFERRED EMBODIMENTS

The embodiments of the present invention are described hereinafter with reference to the accompanying drawings.

The image processing apparatus of the present embodiment of the invention has a controller 1 at it's center for controlling the overall image processing apparatus provided with a CPU. In FIG. 1, the arrows represent the flow of data. A display 2 displays images or text and the like, and displays various types of screens for operation. A keyboard 3 and mouse 4 are used for various input and specified operations. A floppy disk 5 and hard drive 6 are data storage media for storing and saving image data, and the image processing apparatus is provided with a floppy disk drive and a hard disk drive for accessing the floppy disk 5 and the hard disk 6. A printer 7 prints the image data and the like on paper. A scanner 8 reads image data from a document.

A CD-ROM 9 is a storage medium for storing large amounts of various types of image data, and the image processing apparatus is provided with a CD-ROM drive to access the CD-ROM 9. A speaker 10 for audio output and a microphone 11 for audio input are connected. An image processing program described later is read from an external storage medium such as the CD-ROM.

FIG. 2 is a block diagram centered on a controller 1. The controller 1 has a CPU 201 at it center, and connected to this CPU 201 via a data bus 220 are a ROM 203 for storing various processing programs and the like, RAM 204 for storing programs and various data, display control circuit 205 for displaying image and text and the like on the display 2, keyboard control circuit 206 for controlling and transferring input from the keyboard, mouse control circuit 207 for controlling and transferring input from the mouse, floppy disk drive control circuit 208 for controlling the floppy disk drive, hard disk control circuit 209 for controlling the hard disk, printer control circuit 210 for controlling output to the printer 7, scanner control circuit 211 for controlling the scanner 8, CD-ROM drive control circuit 212 for controlling the CD-ROM drive, speaker control circuit 213 for controlling the speaker 10, and a microphone control circuit 214 for controlling the

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microphone 11. Furthermore, a clock circuit 202 supplies
various types of clock signals necessary for the
operation of the image processing apparatus. An
expansion slot 215 is connected so as to allow connection

5   of various types of expansion ports via the data bus.

The controller 1 performs various types of
image processing on a digital image. The digital image
edge enhancement process is described below. FIG. 3
shows the flow of the edge enhancement process performed

10   by the controller 1.

First, image data in the RGB color system are
converted to image data in the HSL color system (step
S10). Then, steps S11~S18 are steps of the edge
enhancement process performed on the L component of the

15   image data in the HSL color system of a specific target
pixel, and these steps are repeated until the edge
enhancement process has been performed on all pixels.

In step S11, a filtering process is executed to
detect the edge. Specifically, a 3×3 pixel block

20   comprising a target pixel and the surrounding pixels is
extracted, and the block is filtered. The coordinates
within this block are defined as shown in FIG. 4. The
pixel at coordinates (2,2) is the target pixel. The edge
detecting matrices w1 used in this filtering is shown in

25   FIGS. 5A through 5D. For example, FIG. 5A is a filter

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for detecting an edge present above the target pixel, and the edge is detected by comparing the value of θ1a determined by equation (1) below to a specific threshold value.

$$\theta 1a = \left| \sum_{i=1, j=1}^{i=2, j=3} X_{ij} wl_{ij} \right| \qquad (1)$$

Where Xij represents the value of L at coordinates (i,j), and wlij represents line i column j component of the edge detecting matrix wl.

Similarly, FIG. 5B is an edge detecting matrix for detecting an edge present below a target pixel, and the edge is detected by comparing the value of θ1b determined by equation (2) below to a specific threshold value.

$$\theta 1b = \left| \sum_{i=2, j=1}^{i=3, j=3} X_{ij} wl_{ij} \right| \qquad (2)$$

Similarly, FIG. 5C is an edge detecting matrix for detecting an edge present to the left of a target pixel, and the edge is detected by comparing the value of θ1c determined by equation (3) below to a specific threshold value.

$$\theta 1c = \left| \sum_{i=1, j=1}^{i=3, j=2} X_{ij} wl_{ij} \right| \qquad (3)$$

Similarly, FIG. 5D is an edge detecting matrix for detecting an edge present to the right of a target

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pixel, and the edge is detected by comparing the value of
θ1d determined by equation (4) below to a specific
threshold value.

$$\theta 1d = \left| \sum_{i=1, j=2}^{i=3, j=3} X_{ij} w l_{ij} \right|$$ (4)

5   In the present embodiment, the edge between
pixels is determined as described above. In this way
edges are naturally enhanced without enhancing only lines
by increasing the difference between both pixels
circumscribing the edge during enhancement. Furthermore,
10   edges present around a target pixel can be limited to
four types by determining the edge between pixels, and
subsequent selection of weighting matrix is simply
accomplished.

          When an edge is detected at a target pixel
15   (step S12: YES), the weighting matrix w2 is selected to
determine the enhancement radius R (step S13). Then, a
block of 5x5 pixels comprising the target pixel and 24
surrounding pixels is extracted, the selected weighting
matrix w2 is used for filtering this block, and the
20   enhancement radius R is determined (step S14). The
coordinates within this block are defined as shown in FIG.
11. FIGS. 12A through 12D show examples of the weighting
matrices w2. FIG. 12A shows a weighting matrix w2 when
an edge is detected at the left side of the target pixel

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(FIG. 7), FIG. 12B shows a weighting matrix w2 when edges
are detected below and on the left side of the target
pixel (FIG. 8), FIG. 12C shows a weighting matrix w2 when
edges are detected below, on the left side and on the
right side of the target pixel (FIG. 9), and FIG. 12D
shows a weighting matrix w2 when an edge is detected on
the left and right sides of the target pixel (FIG. 10).
In all weighting matrices w2, pixels from a11 to a55 are
not 0.

The edge enhancement radius R is a parameter
representing the range for enhancing the edge, and is
used to determine to which pixel to perform enhancement
at the peripheral pixels considered as the edge. For
example, the enhancement radius is 1 (pixel) in the
example of FIG. 6, and the target pixel and surrounding
pixels (shaded area) represent the enhanced pixels
obtained by edge enhancement.

Specifically, the enhancement radius R is
automatically calculated in accordance with equation (5)
below from the image data and weighting matrix w2 using
the radius calculation function F(x).

$$R=F(\Sigma x_{ij}w2_{ij}) \qquad\qquad (5)$$

Where x_{ij} represents the value of L at
coordinates (i,j), and $w2_{ij}$ represents the line i column j
component of the weighting matrix w2.

The radius calculation function F(x) is a function such as shown in the examples below.

F(x)=1 when b1≤x<b2

F(x)=2 when b2≤x<b3

Where b1 and b2 are constants.

The edge enhancement range (enhancement radius) should be determined from the slope (gradation) of the luminance of the edge periphery and edge line type (thickness). The edge enhancement radius is closely related to the edge width. When the edge enhancement radius is small, the edge width is thin, and when the edge enhancement radius is large, the edge width is thick. The edge thickness must be adjusted depending on the object. The weighting in the weighting matrix w2 is at the opposite side (edge inner side) of the edge position relative to the target pixel. Since the edge enhancement radius is determined using the weighting matrix w2, the determined edge enhancement radius is related to the edge width if an edge is in the periphery of the target pixel. When the object is a building, there is a slope point (edge) of acute change in luminance near the object edge, and when the object is a human image, and particularly the photograph of a face, the change in luminance is smooth near the edge. These characteristics are reflected in the edge enhancement radius.

Then, pixels within the enhancement radius R, i.e., the object pixels for edge enhancement processing, are subjected to the enhancement process using the enhancement parameters. Moreover, characteristics of the object can be reflected since the enhancement parameters are determined from the color information and chroma information near the edge. First, the enhancement parameter is calculated for the value $L(i,j)$ of the image data of one object pixel (step S15), and the enhancement process is executed (step S16). This enhancement process is repeated until processing is completed for all object pixels within the enhancement radius R (step S17: YES).

A first enhancement coefficient P1 and a second enhancement coefficient P2 are included in the enhancement parameters, and are calculated from the color information and the enhancement radius as described below.

The first enhancement coefficient P1 is determined from the color information and chroma of the surroundings, i.e., from image data of the target pixel and the eight surrounding pixels. As shown in Table 1, four types of color (neutral color, flesh color, warm color, other) are discriminated to determine the first enhancement coefficient P1.

Table 1

Color	P1	Reason

Neutral color	0.6	Enhance text edge
Flesh color	0.7	Produce skin texture
Warm color	0.7	Soft tones are unnatural with hard edges
Other	1.0	

The second enhancement coefficient P2 is determined by the distance from the center pixel of the enhancement. As shown in Table 2, the second enhancement coefficient P2 is calculated for distances 0, 1, 2 (pixels).

Table 2

Distance	P2
0	1.0
1	0.8
2	0.6

The corrected image data $L'(i,j)$ are calculated by equation (6) below using the uncorrected image data $L(i,j)$, the two enhancement coefficients P1 and P2, and the edge enhancement matrix w3 shown in FIG. 13.

$$L'(i,j)=L(i,j)+W*P1*P2 \qquad (6)$$

$$W=\Sigma L(i,j)*w3ij \qquad (7)$$

Where w3ij represents the line i column j component of the edge enhancement matrix w3.

Although the present invention has been fully described by way of examples with reference to the accompanying drawings, it is to be noted that various changes and modification will be apparent to those skilled in the art. Therefore, unless otherwise such changes and modifications depart from the scope of the present invention, they should be construed as being included therein.

WHAT IS CLAIMED IS:

1. An image processing apparatus, comprising:

edge detecting means for determining the presence/absence of an edge at each pixel of input image data;

selecting means for selecting a weighting matrix corresponding to the position of the edge of each target pixel determined to have an edge by said edge detecting means;

calculating means for calculating data of the target pixel and the pixels surrounding the target pixel using the weighting matrix selected by said selecting means;

enhancement range determining means for determining the range of edge enhancement of the target pixel by comparing the calculation result of said calculating means to a specific threshold value; and

edge enhancing means for executing an edge enhancement process on data of object pixels within the enhancement range determined by said enhancement range determining means.

2. An image processing apparatus according to claim 1, wherein

said enhancement range determining means increases the weighting of components corresponding to the interior side of the edge in the weighting matrix.

3. An image processing apparatus according to claim 1, wherein

said edge detecting means determines the edge to be between pixels.

4. An image processing apparatus according to claim 1, wherein

said enhancement range determining means selects the weighting matrix based on the presence/absence of an edge in four directions surrounding the target pixel.

5. An image processing apparatus according to claim 1, wherein

said edge enhancing means executes processing based on the hue and chroma of the pixels surrounding the object pixel.

6. An image processing apparatus according to claim 1, wherein

said edge enhancing means executes processing based on the distance of the object pixel to the target pixel.

7. An image processing method, comprising the steps of:

determining the presence/absence of an edge at each pixel of input image data;

selecting a weighting matrix corresponding to the position of the edge for each target pixel determined to have an edge;

calculating data of the target pixel and pixels surrounding the target pixel using selected weighting matrix;

comparing the calculation result to a specific threshold value;

determining the range of edge enhancement for the target pixel based on the comparison result; and

executing an edge enhancement process for the object pixels within the determined enhancement range.

8. An image processing method according to claim 7, wherein

the weighting of components corresponding to the interior side of the edge in the weighting matrix is increased in the step of determining the range.

9. A medium readable by a computer storing computer-executable programs comprising the steps of:

determining the presence/absence of an edge at each pixel of input image data;

selecting a weighting matrix corresponding to the position of the edge for each target pixel determined to have an edge;

calculating data of the target pixel and pixels surrounding the target pixel using selected weighting matrix;

comparing the calculation result to a specific threshold value;

determining the range of edge enhancement for the target pixel based on the comparison result; and

executing an edge enhancement process for the object pixels within the determined enhancement range.

10. An image processing apparatus, comprising:

edge detecting means for determining the presence/absence of an edge at each pixel of input image data;

calculating means for calculating data of the target pixel determined to have an edge by said edge detecting means and the pixels surrounding the target pixel using the weighting matrix;

enhancement range determining means for determining the range of edge enhancement of the target pixel by comparing the calculation result of said calculating means to a specific threshold value; and

edge enhancing means for executing an edge enhancement process on data of object pixels within the enhancement range determined by said enhancement range determining means.
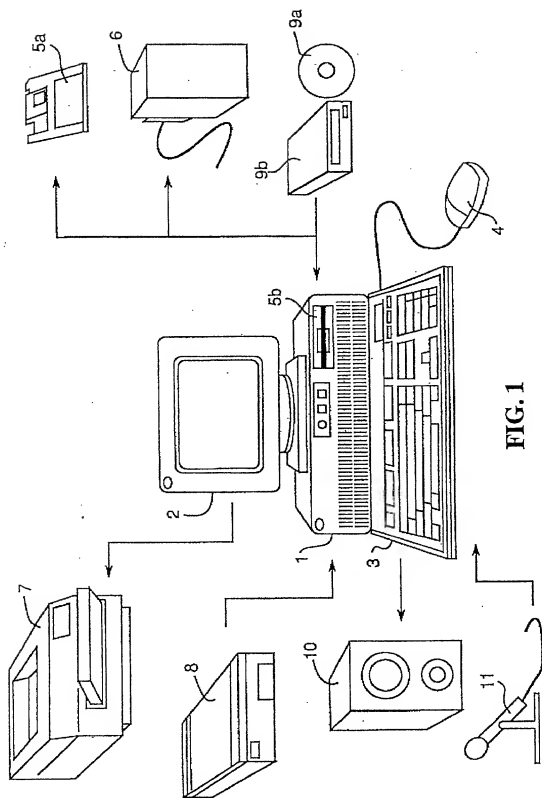
ABSTRACT OF THE DISCLOSURE

Generally, when enhancing the sharpness of a digital image by an edge enhancement process, it is desirable to adjust the range of edge enhancement. For example, when photographing a building or man-made object, the image appears to have an added border when the line of the contour of the building is thickened, such that the image appears unnatural. Accordingly, it is desirable to enhance the line by narrowing the edge enhancement range so as to not thicken the line in the case of buildings and the like. Conversely, when enhancing an edge by thinning the edge in the case of a human image and the like, the enhancement often produces the opposite effect of making the eyes and the like appear unnatural. For this reason it is desirable to smoothly enhance the edge by broadening the width of the edge in the case of human images. In the image processing apparatus of the present invention, the edge enhancement range is determined by calculation using a weighting matrix selected in accordance with the presence/absence of an edge on whichever of the sides of a target pixel. Specifically, data of a target pixel and the surrounding pixels are calculated using a weighting matrix selected by a weighting selection means, and the edge enhancement range is determined by comparing this

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calculated value to a specific threshold value. The data of pixels within the enhancement range determined in this way are subjected to the edge enhancement process.

FIG. 1

FIG. 2

START

RGB=>HSL — S10

EDGE DETECTION — S11

EDGE? — S12
NO
YES

SELECT WEIGHTING MATRIX — S13

DETERMINE ENHANCEMENT RADIUS — S14

CALCULATE ENHANCEMENT PARAMETER — S15

ENHANCEMENT PROCESS — S16

COMPLETED FOR ALL OBJECT PIXELS? — S17
NO
YES

ENHANCEMENT PROCESS ON ALL PIXELS? — S18
NO
YES

RETURN
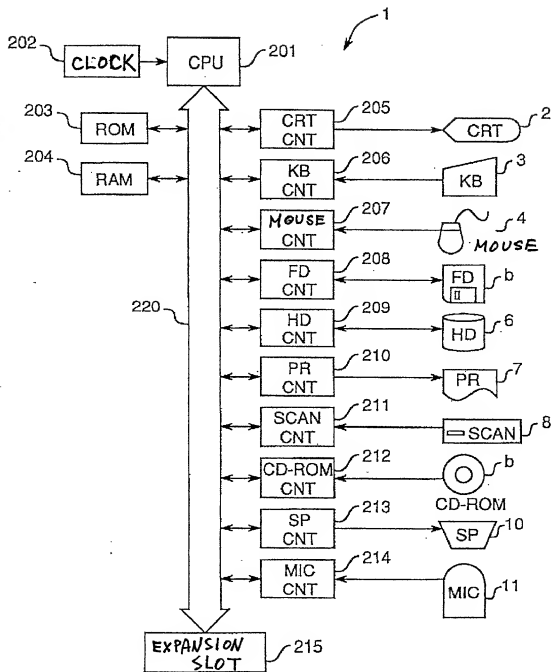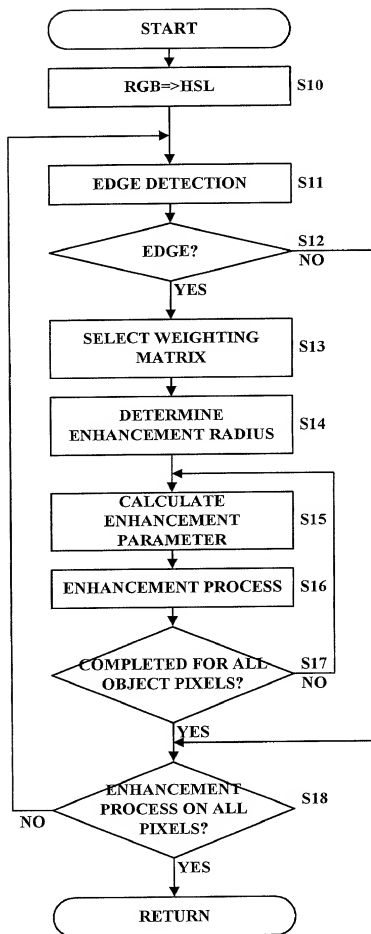
FIG.3

1,1	1,2	1,3
2,1	2,2	2,3
3,1	3,2	3,3

FIG.4

,P	2	1
-1	-2	-1
0	0	0

FIG.5A

0	0	0
,P	2	1
-1	-2	-1

FIG.5B

1	-1	0
2	-2	0
1	-1	0

FIG.5C

0	1	-1
0	2	-2
0	1	-1

FIG.5D
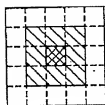
FIG. 6
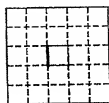
FIG. 7
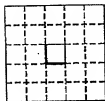
FIG. 8
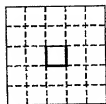
FIG. 9
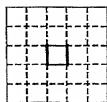
FIG. 10

1,1	1,2	1,3	1,4	1,5
2,1	2,2	2,3	2,4	2,5
3,1	3,2	3,3	3,4	3,5
4,1	4,2	4,3	4,4	4,5
5,1	5,2	5,3	5,4	5,5

FIG.11

0	0	a_{13}	a_{14}	a_{15}
0	0	a_{23}	a_{24}	a_{25}
0	0	a_{33}	a_{34}	a_{35}
0	0	a_{43}	a_{44}	a_{45}
0	0	a_{53}	a_{54}	a_{55}

FIG.12A

a_{11}	a_{12}	a_{13}	a_{14}	a_{15}
0	a_{22}	a_{23}	a_{24}	a_{25}
0	0	a_{33}	a_{34}	a_{35}
0	0	0	a_{44}	a_{45}
0	0	0	0	a_{55}

FIG.12B

a_{11}	a_{12}	a_{13}	a_{14}	a_{15}
0	a_{22}	a_{23}	a_{24}	0
0	0	a_{33}	0	0
0	0	0	0	0
0	0	0	0	0

FIG.12C

0	a_{12}	a_{13}	a_{14}	0
0	a_{22}	a_{23}	a_{24}	0
0	a_{32}	a_{33}	a_{34}	0
0	a_{42}	a_{43}	a_{44}	0
0	a_{52}	a_{53}	a_{54}	0

FIG.12D

-1	-1	-1
-1	8	-1
-1	-1	-1

FIG.13

Attorney Docket No.

COMBINED DECLARATION/POWER OF ATTORNEY FOR PATENT APPLICATION

As a below named inventor, I hereby declare that:

My residence, post office address and citizenship are as stated below next to my name.

I believe I am the original, first and sole inventor (if only one name is listed below) or an original, first and joint inventor (if plural names are listed below) of the subject matter which is claimed and for which a patent is sought on the invention entitled ___IMAGE PROCESSING APPARATUS AND METHOD
___, the specification of which

(check one)   __X__   is attached hereto.

                     ___   was filed on _____ as
                               United States Application No.

                     ___   PCT International Patent Application Number
                               filed
                               and was amended on _____ (if applicable).

I hereby state that I have reviewed and understand the contents of the above identified specification, including the claims, as amended by any amendment referred to above.

I acknowledge the duty to disclose information which is material to the examination of this application in accordance with Title 37, Code of Federal Regulations, § 1.56(a).

I hereby claim foreign priority benefits under Title 35, United States Code, § 119 of any foreign application(s) for patent or inventor's certificate listed below and have also identified below any foreign application for patent or inventor's certificate having a filing date before that of the application on which priority is claimed:

Prior Foreign Application(s)   Priority Claimed

__11-229181__   __Japan___   __13 / August / 1999___   __X__ Yes ___ No
(Number)   (Country)   (Day/Month/Year Filed)

_____   _____   _____   ___ Yes ___ No
(Number)   (Country)   (Day/Month/Year Filed)

I hereby claim the benefit under Title 35, United States Code, § 120 of any United States application(s) listed below and, insofar as the subject matter of each of the claims of this application is not disclosed in the prior United States application in the manner provided by the first paragraph of Title 35, United States Code, § 112, I acknowledge the duty to disclose material information as defined in Title 37, Code of Federal Regulations, § 1.56(a) which occurred between the filing date of the prior application and the national or PCT international filing date of this application:

_____   _____
(Appln. Serial No.)   (Filing Date)   (Status-patented, pending, abandoned)

_____   _____
(Appln. Serial No.)   (Filing Date)   (Status-patented, pending, abandoned)

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Full name of sole or first inventor ___Hiroki YOSHIDA_____

Inventor's signature __*Hiroki Yoshida*____ Date *July 26, 2000*
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